

# Probability and Statistics: Midterm 1 Study Guide

ksv244

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## 1 Introduction to Probability

1. **Probability Measure:** A probability measure on  $(\Omega, F)$  is a function  $P$  from  $f$  to the interval  $[0,1]$  satisfying the following conditions:

(a)  $P(\Omega) = 1$

(b) If  $A_1, A_2, \dots$  are pairwise disjoint in  $F$ , so that  $A_j \cap A_i = \emptyset$  whenever  $i \neq j$ , then  $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$

2. **Probability Space:** The triple  $(\Omega, F, P)$  of objects where:

(a)  $\Omega$  is a set,

(b)  $F$  is an event space made of subsets of  $\Omega$ ,

(c)  $P$  is a **Probability Measure** on  $(\Omega, F)$

1. **Multiplication Principle:** If an experiment has  $m$  outcomes and a second experiment has  $n$  outcomes, there are  $mn$  possible outcomes for the two experiments.

2. **Extended Multiplication Principle:** If there are  $p$  experiments with  $n_1, n_2, \dots, n_p$  possible outcomes, the total of the possible outcomes is  $n_1, n_2, \dots, n_p$  possible outcomes for the  $p$  experiments.

## 2 Conditional Probability

1. If we have a Big Omega =  $\{1, 2, 3, 4, 5, 6\}$  in which we want to find out what is the outcome we will get a specific number (with one roll), it will always be equal to  $\frac{1}{6}$

2. **Calculation for Conditional Probability:**  $P(A|B) = \frac{P(A \cap B)}{P(B)}$

3. **Calc. Conditional Prob. Extended:**  $P(A|B) = \frac{P(A \cap B)P(B)}{P(B)}$

4. **Bayes Rule:**  $P(B_i|A) = \frac{P(A \cap B_i)}{P(A)} = \frac{P(A|B_i)P(B_i)}{\sum_{j=1}^{\infty} P(A|B_j)}$

**Ex:** Suppose you were given the following information:

*In the absence of any special information, the probability that a patient of a certain age has breast cancer is 1%. If the patient has breast cancer, the probability the radiologist will correctly diagnose it is 80%, ( $P(+|B) = 80\%$ ) and ( $P(-|B) = 20\%$ ). If the patient has a benign lesion, the probability that the radiologist will incorrectly diagnose it is 10%, so  $P(-|B^c) = 10\%$ , and  $P(+|B^c) = 90\%$ .*

**Q:** That is the probability that a patient with a positive mammogram actually has breast cancer? **Find:**  $P(B|+)$

Using Bayes Rule, we obtain the equation:  $P(B|+) = \frac{P(+|B)P(B)}{P(+|B)P(B)+P(+|B^c)P(B^c)}$

### 3 Law of Total Probability

1. **The Law of Total Probability**(Partition Thm.):  $\{B_1, B_2, \dots\}$  is a **partition** of  $\Omega$  if  $\cup_i B_i = \Omega$  and  $B_i \cap B_j = \emptyset$  wherever  $i \neq j$ .

### 4 Independence

1. **Independence:** Events  $A$  and  $B$  of a probability space  $(\Omega, F, P)$  are independent if  $P(A \cap B) = P(A)P(B)$  – they are dependent otherwise.
2. **Mutual Independence:** Occurs if the events  $A_1, A_2, \dots, P(\cap_j A_{i_j}) = \pi_j P(A_{i_j})$  for any sub collection  $A_{i_1}, A_{i_2}, \dots$
3. **Pairwise Independence:** occurs if  $P(A_i \cap A_j) = P(A_i)P(A_j)$  whenever  $i \neq j$ .

Events  $A, B, C$  are **pairwise independent**:

$$P(A)P(B) = P(A \cap B), P(A \cap C) = P(A)P(C).$$

**Note:** They are **Mutually Independent** iff  $P(A \cap B \cap C) = P(A)P(B)P(C)$

### 5 Discrete Random Variables:

$$X = \begin{cases} -1 & P(-1) = \frac{1}{2} \\ 1 & P(1) = \frac{1}{2} \end{cases}$$

We have a random variable with values -1 and 1, each with probability  $\frac{1}{2}$ .

To make a d.r.v to determine the different faces we can roll on a dice, it would be as follows..

$$X = \begin{cases} 1 & P(1) = \frac{1}{6} \\ 2 & P(2) = \frac{1}{6} \\ 3 & P(3) = \frac{1}{6} \\ 4 & P(4) = \frac{1}{6} \\ 5 & P(5) = \frac{1}{6} \\ 6 & P(6) = \frac{1}{6} \\ 0 & \text{otherwise} \end{cases}$$

This outlines the possibilities of each number with each roll

**Note:** The term **discrete** refers to the condition that  $X(\Omega)$  is countable.

**Probability Mass Function:** The *pmf*  $p_X(x)$  is the function

$$p_X : R \rightarrow [0, 1]$$

defined by the function  $p_X(x) = P(\{\omega \in \Omega : X(\omega) = x\})$

*ex.* Flip a fair coin and define...

$$Y = \begin{cases} -1 & \text{if } f = T \\ 1 & \text{if } f = H \end{cases}$$

(a) The probability mass function of  $p_Y$  of  $Y$  is given by  $P_Y(1) = P_Y(-1) = \frac{1}{2}$ . The probability of obtaining either is equal to  $\frac{1}{2}$ .

**Cumulative distribution function:** of a random variable  $X$  on the probability space  $(\Omega, F, P)$  is the function  $F_X : R \rightarrow [0, 1]$ , defined by

$$F(X) = F_X(x) = P(X \leq x) = P(\{\omega \in \Omega : X(\omega) \leq x\})$$

**NOTE:** The **cumulative distribution function** is characterized by...

- (1.)  $F_X(x) \leq F_X(y)$  if  $x \leq y$ ,
- (2.)  $\lim_{x \rightarrow -\infty} F_X(x) = 0$  and  $\lim_{x \rightarrow \infty} F_X(x) = 1$
- (3.)  $F_X(x)$  is continuous from the right, that is:

$$\lim_{\epsilon \rightarrow 0^+} F_X(x + \epsilon) = F_X(x)$$

(1.)  $\rightarrow$  Property (1.) holds because

$$\{\omega \in \Omega : X(\omega) \leq x\} \subseteq \{\omega \in \Omega : X(\omega) \leq y\}$$

Wherever,  $x \leq y$ .

(2.)  $\rightarrow$  Property (2.) must be proved.

**Ex:** Proving Cumulative Distribution Function...

**Given:**  $\frac{1}{\pi}\tan^{-1}(x) + \frac{1}{2}$ , prove that it is a cumulative distribution function by checking the three conditions that characterize it.

- (1.)  $F'(x) = \frac{1}{\pi} \frac{1}{1+x^2} \rightarrow$  **Cauchy Density Function**
- (2.)  $\lim_{x \rightarrow -\infty} \frac{1}{\pi}\tan^{-1}(x) + \frac{1}{2} = -\frac{1}{2} + \frac{1}{2} = 0$   
 $\lim_{x \rightarrow \infty} \frac{1}{\pi}\tan^{-1}(x) + \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = 1$
- (3.)  $F$  is continuous because  $\tan^{-1}$  is a continuous function.

## 5.1 Functions of Discrete Random Variables:

If  $X$  is a discrete random variable on  $(\Omega, F, P)$ , and  $g : R \rightarrow R$  is a function, then  $Y = g(X)$  defined by  $Y(\omega) = g(X(\omega)), \forall \omega \in \Omega$  is dully a discrete random variable on  $(\Omega, F, P)$ .

**Note:** The **pmf** of  $Y$  is given by

$$p_Y(y) = P(Y = y) = P(X \in g^{-1}(y)) = \sum_{x^{-1} \cap X(\Omega)} P(X = x)$$

**ex1:**

$$\begin{aligned} g(x) &= ax + b \\ Y = g(X) &= ax + b \\ p_Y(Y) &= P(X = \frac{y-b}{a}), \forall y \in R \end{aligned}$$

**ex2:**

$$\begin{aligned} g(x) &= cx^2 \\ Y = g(X) &= cX^2 \\ p_Y(Y) = p_Y(y) &= \begin{cases} P(X = \sqrt{\frac{y}{c}}) + P(-\sqrt{\frac{y}{c}}) & y > 0 \\ P(X = 0) & y = 0 \\ 0 & y < 0 \end{cases} \end{aligned}$$

## 6 Expectation and Variance:

**Def:** **Mean** or **Expectation** of  $X$  is defined to be:

$$\begin{aligned} E(X) &= \sum_{x \in X(\Omega)} xP(X = x) \\ &= \sum_{x \in X(\Omega)} xp_X(x) \end{aligned}$$

if the sum converges absolutely

**Thm:** If  $X$  is a discrete random variable and  $g : R \rightarrow R_1$ , then the ugly summation of  $g(x)$  is worked into the problem as follows...

$$\sum_{x \in X(\Omega)} g(x)P(X = x)$$

also known as:

$$\sum_{x \in X(\Omega)} g(x)p_X(x)$$

**Def: Variance** of  $X$  is defined as follows:

$$Var(X) = E(X^2) - [E(X)]^2$$

it can be further *complicated* into

$$Var(X) = E[(X - E(X))^2]$$

or

$$E[X^2 - 2XE(X) + E(X)^2],$$

however for the most part it'd be best to just use the initial definition.

## 6.1 Discrete Random Variables - Expectation and Variance (oh how fun):

1. **Bernoulli Distribution:** if  $X(\Omega) = (0, 1)$  annnnnnd,  $P(X = 0) = 1 - p$ , annndddd  $P(X = 1) = p$ , then the Expectation is  $p$ . The Variance, using the formula in Section 6 is

$$Var(X) = E(X^2) - E(X)^2 = p - p^2 = p(1 - p)$$

2. **Binomial Distribution:**  $p_X(x) = P(X = k) = \binom{n}{k}p^k(1 - p)^{n-k}$ .

**Note:**

$$\sum_{k=0}^n P(X = k) = \sum_{k=0}^n \binom{n}{k}p^k(1 - p)^{n-k} = [1 + (1 - p)]^n = 1$$

**Expectation:** The expectation of any binomial random variable is **ALWAYS**  $E(X) = np$ .

**Variance:** The variance of any binomial random variable is **ALWAYS**

$$Var(X) = npq, q = (1 - p).$$

## 6.2 Discrete Random Variables - Continuous Random Variables (oh how much fun):

A **random variable**  $X$  on the probability space  $(\Omega, F, P)$  is a function  $X : \Omega \rightarrow R$  such that

$$\{\omega \in \Omega : X(\omega) \leq x\} \in F, \forall x \in R$$

### 6.3 Density Function:

Typically, continuous random variables that we're interested in have a **density function** of  $f$ , such that  $f(x)$  is greater than or equal to 0 for all real numbers.

$$F_X(x) = P(X \leq x) = \int_{-\infty}^x f(u)du, \forall x \in R$$

If  $X$  has a **continuous** density function  $f$ , the following properties are evident:

$$P(a \leq X \leq b) = F_X(b) - F_X(a) = \int_a^b f(u)du$$
$$\int_{-\infty}^{\infty} f(u)du = 1$$
$$f(x) = \frac{d}{dx}F_X(x)$$

**ex:** The simplest density function is the **uniform density function**:

$$f(x) = \begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & x < a \cup x > b \end{cases}$$

**ex:** As follows is the uniform density on on interval  $[a,b]$ .

$$F_X(x) = \begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & x > b \end{cases}$$

**Note:**  $F_X(x) = \int_{-\infty}^x$  and  $\int_{-\infty}^{\infty} f(u)du = 1$ .  $X$  is a uniform random variable on interval  $[0, 1]$ .

### 6.4 Joint Distributions:

1. If  $X$  and  $Y$  are d.r.v's, the **joint(probability) mass function** of  $X$  and  $Y$  is the function  $p_{X,Y} : R^2 \rightarrow [0, 1]$  defined by the function:

$$p_{X,Y}(x, y) = P(\{\omega \in \Omega : X(\omega) = x, Y(\omega) = y\})$$

**Marginal Mass Function:** The marginal mass function refers to "pulling"  $p_X(x)$  and  $p_Y(y)$  out of the joint function.